rod and given positive charges $q_A$ and $q_B$ . The pucks are set on a smooth (negligible friction) table along with a fixed puck $C$ , which has a negative charge of magnitude $q_C$ .  Using Representations In Case 1, $q_B = 1.4q_A$ , and the $A$ - $B$ -rod system is not fixed and is free to rotate and translate.  In the Case 1 diagram to the right, draw arrows representing only the electric forces exerted on $A$ and $B$ . It is not necessary to label the vectors, but it is necessary that each vector be a distinct arrow that starts on and points away from its point of application and the grid be used to show correct direction and relative magnitudes of forces.  Argumentation  Argumentation  Acceleration is:  Acceleration is:		Scenario  Identical pucks A and B are connected by a nonconducting rigid					
In Case 1, $q_B = 1.4q_A$ , and the $A$ - $B$ -rod system is not fixed and is free to rotate and translate.  In the Case 1 diagram to the right, draw arrows representing only the electric forces exerted on $A$ and $B$ . It is not necessary to label the vectors, but it is necessary that each vector be a distinct arrow that starts on and points away from its point of application and the grid be used to show correct direction and relative magnitudes of forces.  Argumentation  In which direction does the center of the rod accelerate at the instant shown in the diagram? Does the rod rotate clockwise or counterclockwise, if at all? Justify your answers using the forces you drew.  Acceleration is:		rod and given positi smooth (negligible f	ve charges $q_{_A}$ an riction) table alon	$dq_{_B}$ . The pucks $g$ with a fixed po	are set on a	A QA	- QB E
only the electric forces exerted on <i>A</i> and <i>B</i> . It is not necessary to label the vectors, but it is necessary that each vector be a distinct arrow that starts on and points away from its point of application and the grid be used to show correct direction and relative magnitudes of forces.  Argumentation  In which direction does the center of the rod accelerate at the instant shown in the diagram? Does the rod rotate clockwise or counterclockwise, if at all? Justify your answers using the forces you drew.  Acceleration is:	TA:	In Case 1, $q_B = 1.4q_A$ , and the $A$ - $B$ -rod system is not fixed and					<b>@</b> (
In which direction does the center of the rod accelerate at the instant shown in the diagram? Does the rod rotate clockwise or counterclockwise, if at all? Justify your answers using the forces you drew.  Acceleration is:		only the electric forces exerted on $A$ and $B$ . It is not necessary to label the vectors, but it is necessary that each vector be a distinct arrow that starts on and points away from its point of application and the grid be used to show correct direction and					
	ART B:	In which direction does the center of the rod accelerate at the instant shown in the diagram? Does the					
Left Right IIn Down		Acceleration is:					
Helt op bown		Left	Right	Up	Down		
		Countercl	ockwise	Clockwise			

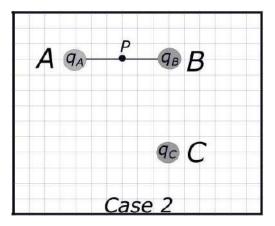
## **Scenario**

In Case 2, the rod is fixed to the table at point P. The magnitude of  $q_{\scriptscriptstyle B}$  is also decreased so that the A-B-rod system is both in translational and rotational equilibrium.

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## **Using Representations**

PART C: In the Case 2 diagram shown at right, draw arrows representing only the external forces exerted on the *A-B*-rod system (For this case, do not draw the normal force and weight, as they are perpendicular to the page). It is not necessary to label the vectors, but it is necessary that each vector be a distinct arrow that starts on and points away from its point of application and the grid be used to show correct direction and relative magnitudes of forces. The forces you draw in the Case 2 diagram do NOT need to be to the same scale as the forces you drew in the Case 1 diagram.



## **Quantitative Analysis**

**PART D:** Derive an expression for the magnitude of charge  $q_{\scriptscriptstyle B}$  in terms of charge  $q_{\scriptscriptstyle A}$ . Verbally explain the physical principles you are using as you perform the steps of your derivation.