

# Describing Motion: Kinematics in One Dimension



AP Physics  
Chapter 2

# Describing Motion: Kinematics in One Dimension



AP Physics

Section 2-1 Reference Frames and Displacement

## Describing Motion: Kinematics in One Dimension

Mechanics – study of motion, force, energy

Kinematics – how objects move

Dynamics – why objects move

Translational Motion – move without rotation

## Describing Motion: Kinematics in One Dimension

Reference Frames (Frames of Reference)

Are we moving?

Compared to what?

Usually with “respect to the Earth”

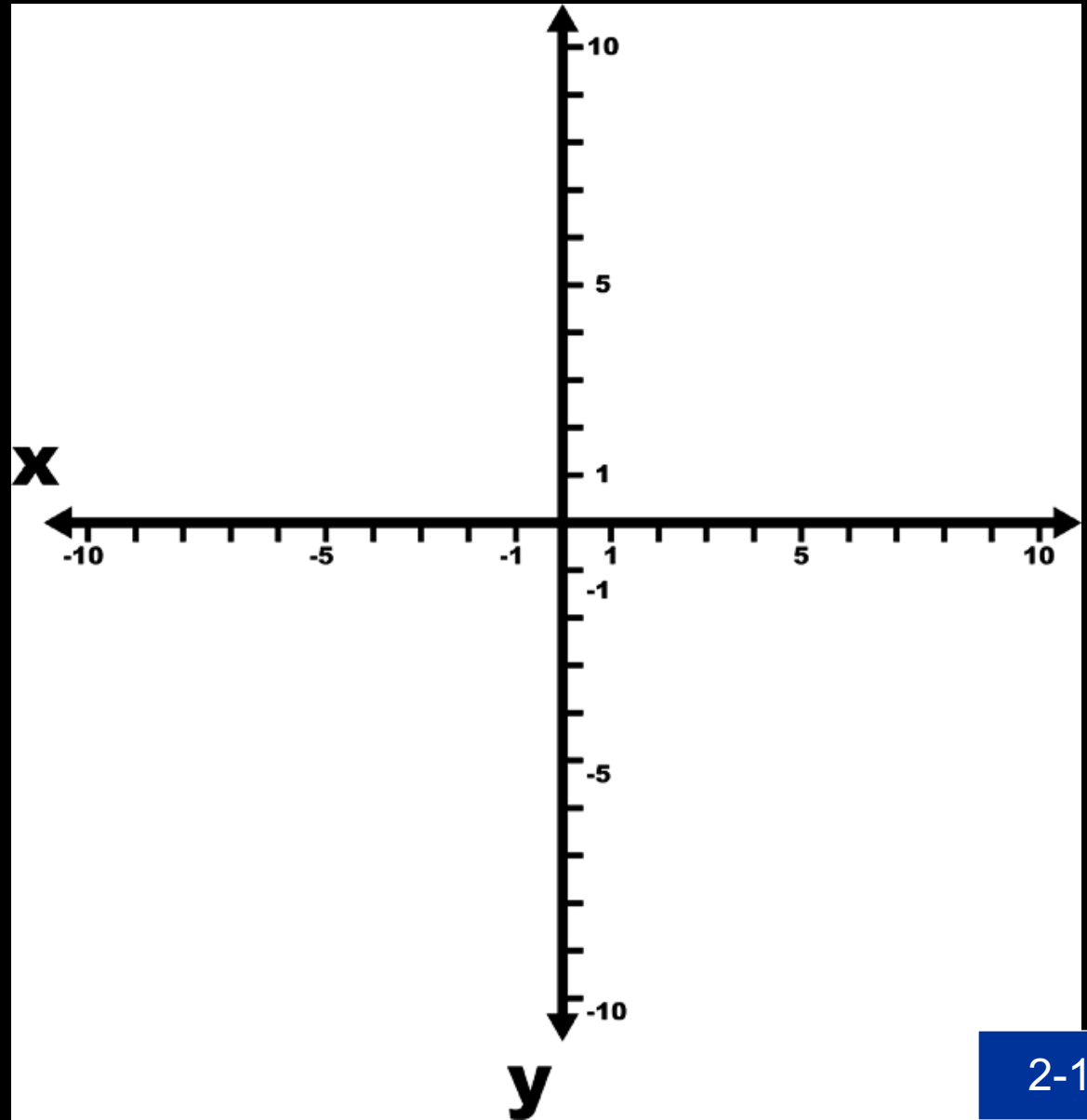
Unless otherwise specified

All other cases, must specify the frame of reference

Typically done with coordinate grid and x and y axis (only x or y for 1D motion)

# Describing Motion: Kinematics in One Dimension

Positive – up  
and right  
Negative –  
down and  
left



# Describing Motion: Kinematics in One Dimension

## Defining Motion

Position – relative to frame of reference (x or y)

Displacement – change in position (meters)

$$\Delta x = x_2 - x_1$$

Not distance!!

# Describing Motion: Kinematics in One Dimension



Distance vs. Displacement

## Describing Motion: Kinematics in One Dimension

1. Distance – scalar (magnitude)
  2. Displacement – vector (magnitude and direction)
    - a. Must give a direction
- For example East/West, up/down



# Describing Motion: Kinematics in One Dimension



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Section 2-2 Average Velocity

## Describing Motion: Kinematics in One Dimension

Average Speed – distance per unit time  
(scalar)

Average Velocity – displacement per unit time  
(vector)(meters/second)

$$\bar{v} = \frac{\Delta x}{\Delta t}$$

$\Delta x$  = displacement

$\Delta t$  = change in time

# Describing Motion: Kinematics in One Dimension



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Section 2-3 Instantaneous Velocity

## Describing Motion: Kinematics in One Dimension

Instantaneous Velocity – the average velocity during an infinitesimally short time interval

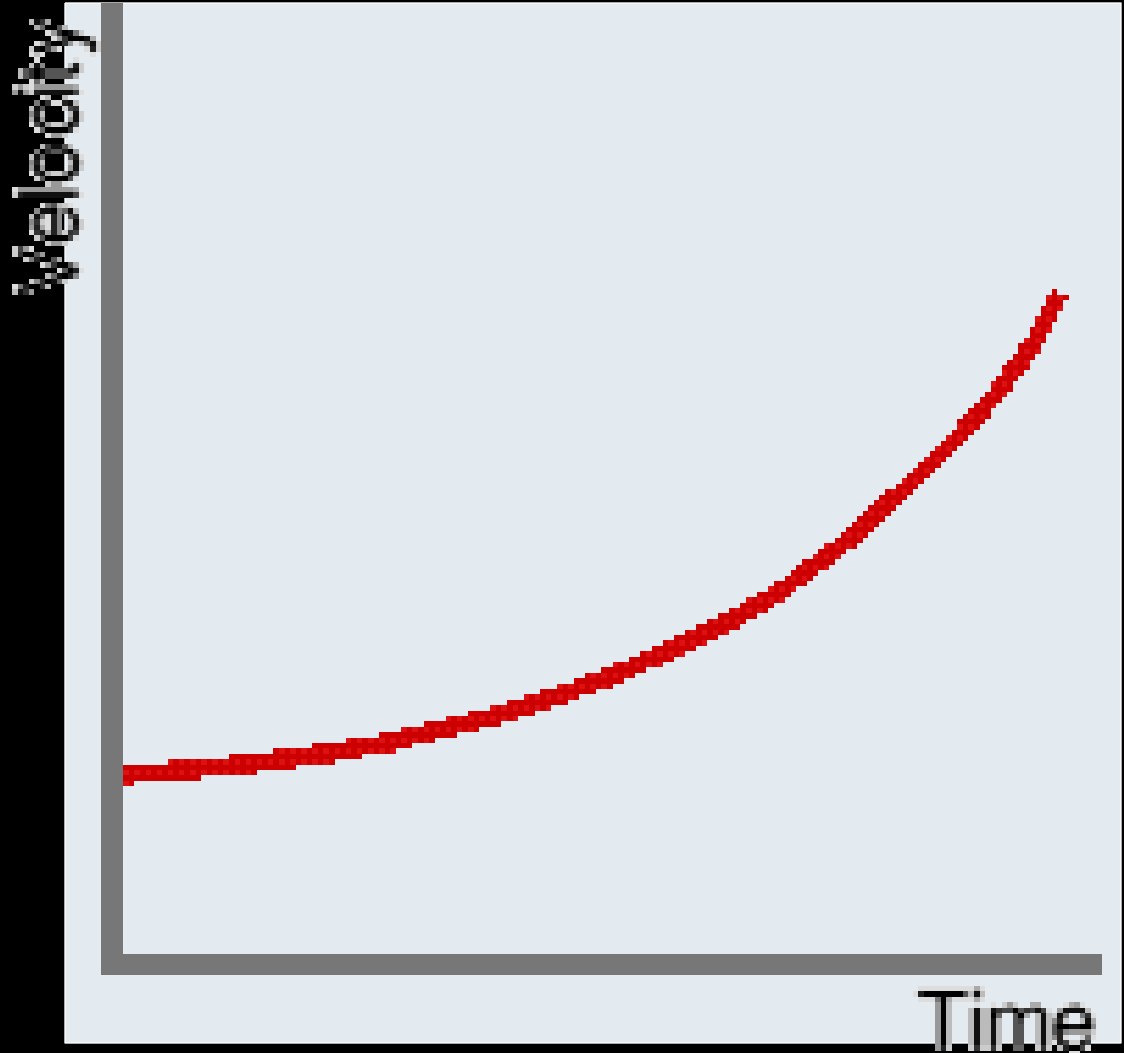
$$v = \lim_{\Delta t \rightarrow 0} \frac{\Delta x}{\Delta t}$$

We will only calculate situations with constant velocity or constant acceleration

Calculus is required if acceleration is not constant

## Describing Motion: Kinematics in One Dimension

Slope of any displacement time graph is the instantaneous velocity



# Describing Motion: Kinematics in One Dimension



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Section 2-4 Acceleration

## Describing Motion: Kinematics in One Dimension

Average Acceleration – change in velocity per unit time (vector) (meters/second<sup>2</sup>)

$$\bar{a} = \frac{\Delta v}{\Delta t} = \frac{v - v_0}{t - t_0}$$

$v$  is final velocity

$v_0$  is initial velocity (or at time 0)

Sign of  $a$  indicates direction of vector

Deceleration is just negative acceleration

## Describing Motion: Kinematics in One Dimension

Acceleration is the slope of the velocity time graph



# Describing Motion: Kinematics in One Dimension



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Section 2-5 Motion at Constant Acceleration

## Describing Motion: Kinematics in One Dimension

We are limited to calculations when acceleration is a constant

We will use the mathematical definition of displacement, velocity, and acceleration to derive 4 Kinematic equations.

**\*\*Memorize these equations – you will use them a lot**

## Describing Motion: Kinematics in One Dimension

Assume

$t_0 = 0$ , it drops out  
of equations

We rework the  
definition of  
acceleration to get  
our first working  
equation

$$a = \frac{v - v_0}{t - t_0}$$

$$a = \frac{v - v_0}{t}$$

$$v = v_0 + at$$

## Describing Motion: Kinematics in One Dimension

For the second equation we first rework the definition of average velocity to solve for displacement

$$\bar{v} = \frac{x - x_0}{t}$$

$$x = x_0 + \bar{v}t$$

## Describing Motion: Kinematics in One Dimension

We define average velocity as the average of the initial and final velocity (only possible with constant acceleration)

$$\bar{v} = \frac{v + v_0}{2}$$

## Describing Motion: Kinematics in One Dimension

Now we combine the last three equations

$$x = x_0 + \bar{v}t$$

$$x = x_0 + \left( \frac{v_0 + v}{2} \right) t$$

$$x = x_0 + \left( \frac{v_0 + v_0 + at}{2} \right) t$$

$$x = x_0 + v_0 t + \frac{1}{2} at^2$$

## Describing Motion: Kinematics in One Dimension

For the third equation we start by using a version of the definition of velocity

$$x = x_0 + \overline{v}t$$

## Describing Motion: Kinematics in One Dimension

Combine with our average velocity definition

$$x = x_0 + \bar{v}t$$

$$x = x_0 + \left( \frac{v_0 + v}{2} \right) t$$



## Describing Motion: Kinematics in One Dimension

Solve the definition  
of acceleration for  
time

$$a = \frac{v - v_0}{t}$$

$$t = \frac{v - v_0}{a}$$

## Describing Motion: Kinematics in One Dimension

Combine and you get

$$x = x_0 + \left( \frac{v_0 + v}{2} \right) t$$

$$x = x_0 + \left( \frac{v_0 + v}{2} \right) \left( \frac{v - v_0}{a} \right)$$

$$x = x_0 + \frac{v^2 - v_0^2}{2a}$$

## Describing Motion: Kinematics in One Dimension

Finally, solve for final velocity

$$x = x_0 + \frac{v^2 - v_0^2}{2a}$$

$$v^2 = v_0^2 + 2ax$$

## Describing Motion: Kinematics in One Dimension

The 4<sup>th</sup> equation is not found in your book, but is in most others

$$x = x_0 + \bar{v}t$$

$$x = x_0 + \left( \frac{v + v_0}{2} \right) t$$

$$x = x_0 + \frac{1}{2} (v + v_0) t$$

# Describing Motion: Kinematics in One Dimension



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Section 2-6 Solving Problems

## Describing Motion: Kinematics in One Dimension

- Determine what the object is your are solving for.
- Draw a diagram. Determine the positive and negative direction for motion.
- Write down any known quantities.
- Think about “The Physics” of the problem.
- Determine what equation, or combination of equations will work under theses Physics conditions.

## Describing Motion: Kinematics in One Dimension

- Make your calculations.
- See if your answer is reasonable.
- Determine what units belong with the number, and what the direction should be if it is a vector.

## Describing Motion: Kinematics in One Dimension

A car slows down uniformly from a speed of 21.0 m/s to rest in 6.00s. How far did it travel in this time?

- Object – car
- Diagram



## Describing Motion: Kinematics in One Dimension

A car slows down uniformly from a speed of 21.0 m/s to rest in 6.00s. How far did it travel in this time?

- Object – car
- Diagram
- Know

$$v_0 = 21.0 \text{ m/s}$$

$$v = 0 \text{ m/s}$$

$$t = 6.00 \text{ s}$$

## Describing Motion: Kinematics in One Dimension

A car slows down uniformly from a speed of 21.0 m/s to rest in 6.00s. How far did it travel in this time?

- Physics – car is going through negative acceleration in 1D, acceleration is constant
- Equation – needs  $v_0$ ,  $v$ ,  $t$ ,  $x$  (define  $x_0=0$ )

So

$$x = x_0 + \frac{1}{2} (v + v_0) t$$

## Describing Motion: Kinematics in One Dimension

A car slows down uniformly from a speed of 21.0 m/s to rest in 6.00s. How far did it travel in this time?

- Physics – car is going through negative acceleration in 1D, acceleration is constant
- Equation – needs  $v_0$ ,  $v$ ,  $t$ ,  $x$  (define  $x_0=0$ )

Solve

$$x = \frac{1}{2} (0 + 21\text{m} / \text{s})(6\text{s}) = 63\text{m}$$

## Describing Motion: Kinematics in One Dimension

A car is behind a truck going  $25\text{m/s}$  on the highway. The car's driver looks for an opportunity to pass, guessing that his car can accelerate at  $1.0\text{m/s}^2$ . He gauges that he has to cover the  $20\text{ m}$  length of the truck, plus  $10\text{ m}$  clear room at the rear of the truck and  $10\text{ m}$  more at the front of it. In the oncoming lane, he sees a car approaching, probably also traveling at  $25\text{ m/s}$ . He estimates that the car is about  $400\text{ m}$  away. Should he attempt to pass?

## Describing Motion: Kinematics in One Dimension

- Object – car
- Diagram

## Describing Motion: Kinematics in One Dimension

- Object – car
- Diagram
- Known quantities

Car relative truck    Car relative to App.    CarApp.    Car

$$v_0 = 0 \text{ m/s} \quad 25 \text{ m/s} \quad 25 \text{ m/s}$$

$$a = 1 \text{ m/s}^2 \quad 1 \text{ m/s}^2 \quad 0 \text{ m/s}^2$$

$$x = 40 \text{ m} \quad 360 \text{ m (why?)}$$

4. Physics – car must travel 40 m to pass truck, approaching car can travel maximum of  $400 - 40$  m in that same period of time, or their paths overlap

## Describing Motion: Kinematics in One Dimension

### 5. Time for car to pass

$$x = x_0 + v_0 t + \frac{1}{2} a t^2$$

$$x = \frac{1}{2} a t^2$$

$$t = \sqrt{\frac{2x}{a}} = \sqrt{\frac{2(40m)}{1m/s^2}}$$

$$t = 8.94s$$

## Describing Motion: Kinematics in One Dimension

5. How far did the other car get in that time?

$$t = 8.94s$$

$$x = vt$$

$$x = (25m / s)(8.94)$$

$$x = 223.5m$$



# Describing Motion: Kinematics in One Dimension



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Section 2-7 Falling Objects (the y-dimension)

## Describing Motion: Kinematics in One Dimension

We will ignore air friction

We will learn the why later.

Acceleration due to gravity at earth's surface is  
 $9.80 \text{ m/s}^2$  directed downward ( $-9.80 \text{ m/s}^2$ )

Symbol  $g$  represents acceleration due to  
gravity

Still use motion equations but

$x$  is replaced with  $y$

$a$  is replaced with  $g$

## Describing Motion: Kinematics in One Dimension

### Two common problems

- Acceleration and velocity are always in the same direction
  - a. No, as an object is thrown upward, velocity is  $+y$ , acceleration is  $-y$
- Acceleration is zero at the highest point.
  - a. No, at the highest point, the velocity is zero, but acceleration is always  $-9.80\text{m/s}^2$
  - b. The object changes velocity, it must have an acceleration