



Robotino		
Motivation: Mobile robots	in smart factories coming up)
Role	Requirements	
Autonomous transport system	free navigation	Intuitive usability
	M2M communication	ability to learn
	w/o overlaid control system	ability to cooperate
		adaptable
		energy-efficient
Mobile manipulator	integrated manipulator	highest availability
Production assistant	inherent safety	lower-cost

Robotino.

Motivation: Supporting research and education in mobile robotics

Research Areas

Navigation Technologies Machine Learning Multi-Sensor Data Fusion Autonomous Systems Artificial Intelligence Co-Operative Robot Systems Mobile Manipulation Service Robotics Applications



Fields of Knowledge

Drive Technology
Motor Control
Sensor Technology
Image Processing
Microcontroller Programming
Service Robotics
Automated Guided Vehicles
Production Logistics

Robotino.

Highlights



Flexible and adaptable design

Scalable CPU performance

Expandable PC and industrial interfaces for extensions

EST

Battery management system

Widespread range of sensor and actuator accessories



Robotino.

Highlights





Adaptive and smooth movement



Robotino							
Facts o	n Senso	ors					
Camera						Optical Sense	ors
Туре	Logitech®	HD Pro C920	•	P.K		Working ran	ge 0 120 mm
Photo		15 MP	1	A		Inductive Ser	isor
Video		full HD 1080p		111/ *	ESTO	Measuring r	ange 0 6 mm
Audio	dual-stere	eo microphone		1/	1	Gyroscope S	ensor
Distance	e Sensors				1	Output data	rate 8 000 Hz
Number a	and type	9 x infrared	in .			Bumper	
Measurin	g range	2 – 40 cm		#		Туре	mechanical switch





Featuring Premium & Basic Edition







Robotino.

Powerful I/O Management



Robotino.





Flexible, adaptable mechanical design









Highlights

Software

Complete open source and Plug & Play concept

Support for all major programming languages and systems

Robotino® Service Portal for system setup and maintenance

Robotino[®] Wiki and Robotino[®] Forum for development of applications

Operating system running on Linux or Windows (in preparation)

Robotino.

Connect your Robotino.!

Maintain via Web Interface



Access to operating & file system via **SSH & SCP**



External programming & control via API



Online programming & remote access via **VNC**



Robotino.

Web Interface





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Robotino.

Simulation





Robotino[®] SIM – The virtual Robotino[®]

Simulates several Robotinos® at one time

Physics simulation based on NVIDIA® PhysX®

Integrated behavior and sensor simulation

Controlled by Robotino[®] View or via API

Entry-level version free-of-charge!

Robotino.

VNC enables programming Robotino. with your smart device



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Support

Robotino[®] Service Portal

Instructions on system setup & operating

Details on components and extensions

Programming getting started

Links to Robotino[®] Wiki and Robotino[®] Forum



botino.						
upport						
		Home Learning Syst	ems Training and Consu	Ilting Services Con	npany News	
	References Help	Hardware				
→ Robotino [®] Servio		9	8			
→ www.robotino.com	Robotino®					
→ www.robotino.com	Robotino® Hardware			1		
 → www.robotino.com → Robotino[®] Wiki 	Robotino© Hardware Control Drive systems	Control	Drive systems	Sensors	Interfaces	Supply
 → www.robotino.com → Robotino[®] Wiki 	Robotino® Hardware Control Drive systems Sensors Interface	Control → Power switch	Drive systems > Omnidrive	Sensors → Bumper	Interfaces → WLAN	Supply → Batteries
 → www.robotino.com → Robotino[®] Wiki → Robotino[®] Forum 	Robotino® Hardware Control Drive systems Sensors Interface Supply	Control → Power switch → Control unit	Drive systems → Omnidrive → Motors	Sensors → Bumper → Distance sensors	Interfaces → WLAN → I/O-Interfaces	Supply → Batteries → Power supply unit
 → www.robotino.com → Robotino[®] Wiki → Robotino[®] Forum 	Robotino® Hardware Control Drive systems Sensors Interface Supply Web interface Programming	Control → Power switch → Control unit → Embedded PC	Drive systems → Omnidrive → Motors → Incremental encoder	Sensors → Bumper → Distance sensors → Gyroscope	Interfaces → WLAN → I/O-Interfaces → Motor/encoder	Supply → Batteries → Power supply unit → Charging electronics
 → www.robotino.com → Robotino[®] Wiki → Robotino[®] Forum 	Robotino® Hardware Control Drive systems Sensors Interface Supply Web interface Programming Simulation	Control → Power switch → Control unit → Embedded PC → Microcontroller	Drive systems → Omnidrive → Motors → Incremental encoder → Gear units	Sensors → Bumper → Distance sensors → Gyroscope → Camera	Interfaces → WLAN → I/O-Interfaces → Motor/encoder → USB	Supply → Batteries → Power supply unit → Charging electronics → Pedestal
 → www.robotino.com → Robotino[®] Wiki → Robotino[®] Forum 	Robotino® Hardware Control Drive systems Sensors Interface Supply Web interface Programming Simulation Tools Support	Control → Power switch → Control unit → Embedded PC → Microcontroller → Reset button	Drive systems → Omnidrive → Motors → Incremental encoder → Gear units → Wheels	Sensors > Bumper > Distance sensors > Gyroscope > Camera > Opto-electronic sensors	Interfaces → WLAN → I/O-Interfaces → Motor/encoder → USB → PCI Express	Supply → Batteries → Power supply unit → Charging electronics → Pedestal
 → www.robotino.com → Robotino[®] Wiki → Robotino[®] Forum 	Robotino® Hardware Control Drive systems Sensors Interface Supply Web interface Programming Simulation Tools Support Robotino® XXT	Control → Power switch → Control unit → Embedded PC → Microcontroller → Reset button	Drive systems → Omnidrive → Motors → Incremental encoder → Gear units → Wheels	Sensors > Bumper > Distance sensors > Gyroscope > Camera > Opto-electronic sensors > Inductive sensors	Interfaces VULAN VULAN I/O-Interfaces VOSB VOSB PCI Express Ethernet	Supply → Batteries → Power supply unit → Charging electronics → Pedestal





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Robotino.

Teachware

Robotino®		Repetitio Workbook
	FESTO	Project 1 Inspection of supplied components and commissioning of the Robotino
	MI CONCH	Project 2 Linear travelling of a mobile robot system in any direction
		Project 3 Linear travelling and positioning of a mobile robot system
		Project 4 Path tracking of an automated guided vehicle system using two diffuse sensors
		Project 5 Accurately positioned approach of a loading station
	Telle Didado : Bizzlenia	Project 6 Approaching an obstacle and maintaining a defined distance

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Teachware

	FESTO Adetasch	Project 7 Circling a station and approaching various transfer positions
-	NE CORON	Project 8 Path tracking of an automated guided vehicle system using an analogue inductive sensor
		Project 9 Determining the optimal motion behaviour
		Project 10 Path tracking of an automated guided vehicle system with the phelp of a webcam
		Project 11 Searching and approaching a coloured object with the help of a webcam











Robotino. at the RoboCup



RoboCup Logistics League

An interdisciplinary challenge in the fields of mechatronics, computer science and logistics has to be answered with a flexible yet precise autonomous solution based on mobile robots.

Festo sponsors the RoboCup since 2006

RoboCup 2009 in Graz, Austria Festo Hockey Challenge with 6 teams RoboCup 2010 in Singapore Festo Logistics Competition with 9 teams RoboCup 2011 in Istanbul, Turkey Festo Logistics Competition with 15 teams

Official RoboCup Logistics League sponsored by Festo since 2012





Robotino. at the RoboCup



RoboCup Logistics League

RoboCup World 2015 in Hefei, China RoboCup World 2016 in Leipzig, Germany





Robotino. at the RoboCup



RoboCup Robotino[®] RoboCup Set – Special Offer 2015

Up to three sets of the Robotino[®] RoboCup Set are available for each team participating at the RoboCup Logistics League sponsored by Festo within 12 months.



1 x Robotino[®] Premium Edition (order no.: 8029256) including:

Intel[®] Core i5 with 2.4 GHz, 64 GB SSD, 8 GB RAM

- 2 x optical sensors
- 1 x inductive sensor
- 1 x assembly tower with1 x backbone, 3 x plates

1 x Set of Workpieces (order no.: 554301)

Special total price for customers: 5 500 EUR plus tax



