

Content				
Unit	Topics	Labs/Activities	Big Ideas	Learning Objectives/Science Practices
1. KINEMATICS [CR2a]	<ul style="list-style-type: none"> <li>• Kinematics in one-dimension: constant velocity and uniform accelerated motion</li> <li>• Vectors: vector components and resultant</li> <li>• Kinematics in two-dimensions: projectile motion</li> </ul>	<p><b>1. Match the Graph (GI) [CR6b]</b> To determine the proper placement of an air track, a glider, and a motion detector to produce a motion that matches a set of given graphs: position, velocity, and acceleration versus time.</p> <p><b>2. Free-Fall Investigation</b> To determine and compare the acceleration of two objects dropped simultaneously.</p> <p><b>3. Vector Addition (GI) [CR6b]</b> To determine the value of a resultant of several vectors, and then compare that value to the values obtained through graphical and analytical methods.</p> <p><b>4. Shoot the Target (GI) [CR6b]</b> To determine the initial velocity of a projectile, the angle at which the maximum range can be attained, and predict where the projectile will land.</p> <p><b>5. Chase Scenario (GI) [CR6b]</b> <i>Lab Practicum:</i> Students use a battery cart and a fan cart to recreate a chase scenario (police-thief) to predict the position where the ‘thief’ will be caught and the final speeds of</p>	3	<p><b>Learning Objectives:</b> 3.A.1.1, 3.A.1.2, 3.A.1.3</p> <p><b>Science Practices</b> 1.2, 1.5, 2.1, 2.2, 3.1, 4.1, 4.2, 4.3, 5.1, 5.3, 6.1, 6.4, 7.2</p> <p><b>Science Practices</b> 1.4, 2.1, 2.2, 3.1, 4.1, 4.2, 4.3, 5.1, 5.3, 6.1, 6.4, 7.2</p> <p><b>Science Practices</b> 1.1, 1.2, 1.4, 2.1, 2.2, 3.1, 4.1, 4.2, 4.3, 5.3, 6.1, 6.4, 7.2</p> <p><b>Science Practices</b> 1.4, 1.5, 2.1, 2.2, 3.1, 4.1, 4.2, 4.3, 5.3, 6.1, 6.4, 7.2</p> <p><b>Science Practices</b> 1.1, 1.2, 1.4, 1.5, 2.1, 2.2, 3.1, 3.2, 3.3, 4.1, 4.2, 4.3, 5.1, 5.2, 5.3, 6.1, 6.2, 6.4, 7.2</p>

		both cars.		
<b>2. DYNAMICS [CR2b]</b>	<ul style="list-style-type: none"> <li>Forces, types, and representation (FBD)</li> <li>Newton's First Law</li> <li>Newton's Third Law</li> <li>Newton's Second Law</li> <li>Applications of Newton's Second Law</li> <li>Friction</li> <li>Interacting objects: ropes and pulleys</li> </ul>	<p><b>6. Inertial and Gravitational Mass (GI) [CR6b]</b> To determine the difference (if any) between inertial mass and gravitational mass.</p> <p><b>7. Forces Inventory (GI) [CR6b]</b> Qualitative and quantitative investigation on a variety of interactions between objects.</p> <p><b>8. Static Equilibrium Challenge</b> To determine the mass of a hanging object in a setup with three strings at various angles.</p> <p><b>9. Newton's Second Law (OI) [CR6b]</b> To determine the variation of the acceleration of a dynamics cart in two scenarios: (1) the total mass of the system is kept constant while the net force varies, and (2) the net force is kept constant while the total mass of the system varies.</p> <p><b>10. Coefficient of Friction (GI) [CR6b]</b> To determine the maximum coefficient of static friction between a shoe and a wooden plank.</p> <p><b>11. Atwood's Machine (GI) [CR6b]</b> To determine the acceleration of</p>	1,2,3,4	<p><b>Learning Objectives:</b> 1.C.1.1, 1.C.1.3, 2.B.1.1, 3.A.2.1, 3.A.3.1, 3.A.3.2, 3.A.3.3, 3.A.4.1, 3.A.4.2, 3.A.4.3, 3.B.1.1, 3.B.1.2, 3.B.1.3, 3.B.2.1, 3.C.4.1, 3.C.4.2, 4.A.1.1, 4.A.2.1, 4.A.2.2, 4.A.2.3, 4.A.3.1, 4.A.3.2</p> <p><b>Science Practices</b> 1.4, 2.1, 2.2, 3.1, 4.1, 4.2, 4.3, 5.3, 6.1, 6.4, 7.2</p> <p><b>Science Practices</b> 1,1, 1.4, 1.5, 2.1, 2.2, 3.3, 4.1, 4.2, 4.3, 5.1, 6.1, 6.2, 6.4, 7.2</p> <p><b>Science Practices</b> 1.1, 1.4, 2.1, 2.2, 3.1, 4.1, 4.2, 4.3, 5.1, 5.3, 6.1, 6.4,7.2</p> <p><b>Science Practices</b> 1.1, 1.4, 1.5, 2.1, 2.2, 3.1, 3.2, 3.3, 4.1, 4.2, 4.3, 5.1, 5.2, 5.3, 6.1, 6.2, 6.4, 7.2</p> <p><b>Science Practices</b> 1.1, 1.4, 1.5, 2.1, 2.2, 3.1, 4.1, 4.2, 4.3, 5.3, 6.1, 6.4,7.2</p> <p><b>Science Practices</b> 1.1, 1.4, 1.5, 2.1, 2.2, 3.1, 4.1, 4.2, 4.3, 5.3, 6.1, 6.4,7.2</p>

<p><b>2. DYNAMICS</b> [CR2b]</p>	<ul style="list-style-type: none"> <li>• Forces, types, and representation (FBD)</li> <li>• Newton’s First Law</li> <li>• Newton’s Third Law</li> <li>• Newton’s Second Law</li> <li>• Applications of Newton’s Second Law</li> <li>• Friction</li> <li>• Interacting objects: ropes and pulleys</li> </ul>	<p><b>6. Inertial and Gravitational Mass (GI) [CR6b]</b> To determine the difference (if any) between inertial mass and gravitational mass.</p> <p><b>7. Forces Inventory (GI) [CR6b]</b> Qualitative and quantitative investigation on a variety of interactions between objects.</p> <p><b>8. Static Equilibrium Challenge</b> To determine the mass of a hanging object in a setup with three strings at various angles.</p> <p><b>9. Newton’s Second Law (OI) [CR6b]</b> To determine the variation of the acceleration of a dynamics cart in two scenarios: (1) the total mass of the system is kept constant while the net force varies, and (2) the net force is kept constant while the total mass of the system varies.</p> <p><b>10. Coefficient of Friction (GI) [CR6b]</b> To determine the maximum coefficient of static friction between a shoe and a wooden plank.</p> <p><b>11. Atwood’s Machine (GI) [CR6b]</b> To determine the acceleration of a hanging mass and the tension in the string.</p>	<p>1,2,3, 4</p>	<p><b>Learning Objectives:</b> 1.C.1.1, 1.C.1.3, 2.B.1.1, 3.A.2.1, 3.A.3.1, 3.A.3.2, 3.A.3.3, 3.A.4.1, 3.A.4.2, 3.A.4.3, 3.B.1.1, 3.B.1.2, 3.B.1.3, 3.B.2.1, 3.C.4.1, 3.C.4.2, 4.A.1.1, 4.A.2.1, 4.A.2.2, 4.A.2.3, 4.A.3.1, 4.A.3.2</p> <p><b>Science Practices</b> 1.4, 2.1, 2.2, 3.1, 4.1, 4.2, 4.3, 5.3, 6.1, 6.4, 7.2</p> <p><b>Science Practices</b> 1.1, 1.4, 1.5, 2.1, 2.2, 3.3, 4.1, 4.2, 4.3, 5.1, 6.1, 6.2, 6.4, 7.2</p> <p><b>Science Practices</b> 1.1, 1.4, 2.1, 2.2, 3.1, 4.1, 4.2, 4.3, 5.1, 5.3, 6.1, 6.4,7.2</p> <p><b>Science Practices</b> 1.1, 1.4, 1.5, 2.1, 2.2, 3.1, 3.2, 3.3, 4.1, 4.2, 4.3, 5.1, 5.2, 5.3, 6.1, 6.2, 6.4, 7.2</p> <p><b>Science Practices</b> 1.1, 1.4, 1.5, 2.1, 2.2, 3.1, 4.1, 4.2, 4.3, 5.3, 6.1, 6.4,7.2</p> <p><b>Science Practices</b> 1.1, 1.4, 1.5, 2.1, 2.2, 3.1, 4.1, 4.2, 4.3, 5.3, 6.1, 6.4,7.2</p>
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<p><b>5. MOMENTUM [CR2e]</b></p>	<ul style="list-style-type: none"> <li>• Impulse</li> <li>• Momentum</li> <li>• Conservation of momentum</li> <li>• Elastic and inelastic collisions</li> </ul>	<p><b>16. Bumper Design (GI) [CR6b]</b> To design a paper bumper that will soften the impact of the collision between a cart and a fixed block of wood. Their designs are evaluated by the shape of an acceleration-versus-time graph of the collision.</p> <p><b>17. Impulse and Change in Momentum (GI) [CR6b]</b> To measure the change in momentum of a dynamics cart and compare it to the impulse received.</p> <p><b>18. Elastic and Inelastic Collisions (OI) [CR6b]</b> To investigate conservation of momentum and conservation of energy using a ballistic pendulum to determine the type of collision.</p> <p><b>19. Forensic Investigation (OI) [CR6b]</b> <i>Lab Practicum:</i> Apply principles of conservation of energy, conservation of momentum, the work-energy theorem, and a linear model of friction to find the coefficient of kinetic friction.</p>	<p>3,4,5</p>	<p><b>Learning Objectives:</b> 3.D.1.1, 3.D.2.1, 3.D.2.2, 3.D.2.3, 3.D.2.4, 4.B.1.1, 4.B.1.2, 4.B.2.1, 4.B.2.2, 5.A.2.1, 5.D.1.1, 5.D.1.2, 5.D.1.3, 5.D.1.4, 5.D.1.5, 5.D.2.1, 5.D.2.2, 5.D.2.3, 5.D.2.4, 5.D.2.5, 5.D.3.1</p> <p><b>Science Practices</b> 1.4, 2.1, 2.2, 3.1, 3.2, 4.1, 4.2, 4.3, 5.1, 5.2, 5.3, 6.1,6.2, 6.4, 7.2</p> <p><b>Science Practices</b> 1.1, 1.2, 1.3, 1.4, 1.5, 2.1, 2.2, 3.1, 4.1, 4.2, 4.3, 5.1,5.3, 6.1, 6.4, 7.2</p> <p><b>Science Practices</b> 1.1, 1.2, 1.3, 1.4, 1.5, 2.1, 2.2, 3.1, 4.1, 4.2, 4.3, 5.1,5.2, 5.3, 6.1, 6.2, 6.4, 7.2</p> <p><b>Science Practices</b> 1.1, 1.2, 1.4, 1.5, 2.1, 2.2, 3.1, 3.2, 3.3, 4.1, 4.2, 4.3, 5.1, 5.2, 5.3, 6.1, 6.2, 6.4, 7.2</p>
<p><b>6. SIMPLE HARMONIC MOTION [CR2d]</b></p>	<ul style="list-style-type: none"> <li>• Linear restoring forces and simple harmonic motion</li> <li>• Simple harmonic motion graphs</li> <li>• Simple pendulum</li> <li>• Mass-spring systems</li> </ul>	<p><b>20. Finding the Spring Constant (GI) [CR6b]</b></p>	<p>3,5</p>	<p><b>Learning Objectives:</b> 3.B.3.1, 3.B.3.2, 3.B.3.3, 3.B.3.4, 5.B.2.1, 5.B.3.1, 5.B.3.2, 5.B.3.3, 5.B.4.1, 5.B.4.2</p> <p><b>Science Practices</b> 1.1, 1.4, 2.1, 2.2, 3.1, 4.1, 4.2, 4.3, 5.3, 6.1, 6.4, 7.2</p>

		<p>To design two independent experiments to determine the spring constants of various springs of equal length.</p> <p><b>21. Graphs of an Oscillating System (GI) [CR6b]</b> To analyze graphs of position, velocity, and acceleration versus time for an oscillating system to determine how velocity and acceleration vary at the equilibrium position and at the endpoints.</p> <p><b>22. Simple Pendulum Investigation (GI) [CR6b]</b> To investigate the factors that affect the period of a simple pendulum and test whether the period is proportional to the pendulum's length, the square of its length, or the square root of its length.</p>		<p><b>Science Practices</b> 1.1, 1.2, 1.4, 1.5, 2.1, 2.2, 3.1, 4.1, 4.2, 4.3, 5.1, 5.3,6.1, 6.4, 7.2</p> <p><b>Science Practices</b> 1.2, 1.4, 2.1, 2.2, 2.3, 3.1, 3.2, 3.3, 4.1, 4.2, 4.3, 5.1,5.3, 6.1, 6.4, 7.2</p>
7.ROTATIONAL MOTION[CR2g]	<ul style="list-style-type: none"> <li>• Torque</li> <li>• Center of mass</li> <li>• Rotational kinematics</li> <li>• Rotational dynamics and rotational inertia</li> <li>• Rotational energy</li> <li>• Angular momentum</li> <li>• Conservation of angular momentum</li> </ul>	<p><b>23. Torque and the Human Arm (OI) [CR6b]</b> To design and build an apparatus that replicates the forearm and biceps muscle system to determine the biceps tension when holding an object in a lifted position.</p> <p><b>24. Rotational Inertia (GI) [CR6b]</b> To determine the rotational inertia of a cylinder from the slope of a graph of an applied torque versus angular</p>	3,4,5	<p><b>Learning Objectives:</b> 3.F.1.1, 3.F.1.2, 3.F.1.3, 3.F.1.4, 3.F.1.5, 3.F.2.1, 3.F.2.2, 3.F.3.1, 3.F.3.2, 3.F.3.3, 4.A.1.1, 4.D.1.1, 4.D.1.2, 4.D.2.1, 4.D.2.2, 4.D.3.1, 4.D.3.2, 5.E.1.1, 5.E.1.2, 5.E.2.1</p> <p><b>Science Practices</b> 1.1, 1.2, 1.4, 1.5, 2.1, 2.2, 3.1, 4.1, 4.2, 4.3, 5.1, 5.2, 5.3, 6.1, 6.2, 6.4, 7.1, 7.2</p> <p><b>Science Practices</b> 1.1, 1.2, 1.4, 1.5, 2.1, 2.2, 3.1, 4.1, 4.2, 4.3, 5.1, 5.3,6.1, 6.4, 7.2</p>

		<p>acceleration.</p> <p><b>25. Conservation of Angular Momentum (GI) [CR6b]</b> To investigate how the angular momentum of a rotating system responds to changes in the rotational inertia.</p>		<p><b>Science Practices</b> 1.1, 1.2, 1.4, 1.5, 2.1, 2.2, 3.1, 4.1, 4.2, 4.3, 5.1, 5.3,6.1, 6.4, 7.2</p>
<p><b>8.MECHANICAL WAVES[CR2j]</b></p>	<ul style="list-style-type: none"> <li>• Traveling waves</li> <li>• Wave characteristics</li> <li>• Sound</li> <li>• Superposition</li> <li>• Standing waves on a string</li> <li>• Standing sound waves</li> </ul>	<p><b>26. Mechanical Waves (GI) [CR6b]</b> To model the two types of mechanical waves with a spring toy to test whether or not these characteristics affect the speed of a pulse: frequency, wavelength, and amplitude.</p> <p><b>27. Speed of Sound (GI) [CR6b]</b> Design two different procedures to determine the speed of sound in air.</p> <p><b>28. Wave Boundary Behavior (GI) [CR6b]</b> To compare what happens to the phase of a transverse wave on a spring toy when a pulse is reflected from a boundary and when it is reflected and transmitted from various boundaries (spring to string).</p> <p><b>29. Standing Waves (GI) [CR6b]</b> Given a specified tension, students predict the length of the string necessary to generate the first two harmonics of a</p>	<p>6</p>	<p><b>Learning Objectives:</b> 6.A.1.1, 6.A.1.2, 6.A.1.3, 6.A.2.1, 6.A.3.1, 6.A.4.1, 6.B.1.1, 6.B.2.1, 6.B.4.1, 6.B.5.1, 6.D.1.1, 6.D.1.2, 6.D.1.3, 6.D.2.1, 6.D.3.1, 6.D.3.2, 6.D.3.3, 6.D.3.4, 6.D.4.1, 6.D.4.2, 6.D.5.1</p> <p><b>Science Practices</b> 1.2, 2.1, 2.2, 3.1, 4.1, 4.2, 4.3, 5.1, 5.3, 6.1, 6.2, 6.4,7.2</p> <p><b>Science Practices</b> 1.1, 1.2, 1.4, 1.5, 2.1, 2.2, 3.1, 4.1, 4.2, 4.3, 5.3, 6.1,6.4, 7.2</p> <p><b>Science Practices</b> 1.4, 3.1, 4.1, 4.2, 4.3, 5.1, 6.1, 6.4, 7.2</p> <p><b>Science Practices</b> 1.1, 1.2, 1.4, 1.5, 2.1, 2.2, 3.1, 4.1, 4.2, 4.3, 5.1, 5.3,6.1, 6.4, 7.2</p>

		standing wave on the string. Then they perform the experiment and compare the outcome with their prediction.		
9.ELECTROSTATICS [CR2h]	<ul style="list-style-type: none"> <li>• Electric charge and conservation of charge</li> <li>• Electric force: Coulomb's Law</li> </ul>	<p><b>30. Static Electricity Interactions (GI) [CR6b]</b> Students use sticky tape and a variety of objects to make qualitative observations of the interactions when objects are charged, discharged, and recharged.</p> <p><b>31. Coulomb's Law (GI) [CR6b]</b> To estimate the charge on two identical, equally charged spherical pith balls of known mass.</p>	1,3,5	<p><b>Learning Objectives:</b> 1.B.1.1, 1.B.1.2, 1.B.2.1, 1.B.3.1, 3.C.2.1, 3.C.2.2, 5.A.2.1</p> <p><b>Science Practices</b> 1.2, 3.1, 4.1, 4.2, 5.1, 6.2, 7.2</p> <p><b>Science Practices</b> 1.1, 1.2, 1.4, 1.5, 2.1, 2.2, 3.1, 4.1, 4.2, 4.3, 5.1, 5.3, 6.1, 6.4, 7.2</p>
10.DC CIRCUITS [CR2i]	<ul style="list-style-type: none"> <li>• Electric resistance</li> <li>• Ohm's Law</li> <li>• DC circuits</li> <li>• Series and parallel connections</li> <li>• Kirchoff's Laws</li> </ul>	<p><b>32. Brightness Investigation (GI) [CR6b]</b> To make predictions about the brightness of light bulbs in a variety of series and parallel circuits when some of the bulbs are removed.</p> <p><b>33. Voltage and Current (GI) [CR6b]</b> To determine the relationship between the current through a resistor and the voltage across the resistor.</p> <p><b>34. Resistance and Resistivity</b></p>	1,5	<p><b>Learning Objectives:</b> 1.B.1.1, 1.B.1.2, 1.E.2.1, 5.B.9.1, 5.B.9.2, 5.B.9.3, 5.C.3.1, 5.C.3.2, 5.C.3.3</p> <p><b>Science Practices</b> 1.2, 3.1, 4.1, 4.2, 4.3, 5.3, 6.1, 6.4, 7.2</p> <p><b>Science Practices</b> 1.1, 1.2, 1.4, 1.5, 2.1, 2.2, 3.1, 4.1, 4.2, 4.3, 5.1, 5.3, 6.1, 6.4, 7.2</p> <p><b>Science Practices</b> 1.4, 2.1, 2.2, 3.1, 4.1, 4.2, 4.3, 5.1, 5.3,</p>

		<p><b>(GI) [CR6b]</b>          To investigate the effects of cross-sectional area and length on the flow of current through a roll of Play-Doh.</p> <p><b>35. Series and Parallel Circuits (GI) [CR6b]</b>          To investigate the behavior of resistors in series, parallel, and series-parallel circuits. The lab should include measurements of voltage and current.</p>	<p>6.1, 6.4, 7.2</p> <p><b>Science Practices</b> 1.1, 1.2, 1.4, 1.5, 2.1, 2.2, 3.1, 4.1, 4.2, 4.3, 5.1, 5.2,5.3, 6.1, 6.4, 7.2</p>
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